

# LM4863 Boomer® Audio Power Amplifier Series

## Dual 1.1W Audio Amplifier plus Stereo Headphone Function

### General Description

The LM4863 is a dual bridge-connected audio power amplifier capable of delivering 1.1W of continuous average power to an 8Ω load with less than 0.5% (THD) using a 5V power supply. In addition, enabling the headphone input pin allows the amplifiers to be operated in single-ended mode to drive stereo headphones.

Boomer audio power amplifiers were designed specifically to provide high quality output power from a surface mount package while requiring a minimal amount of external components. Since the LM4863 incorporates both dual bridge speaker drive and stereo headphone functionality on chip, it is optimally suited for multimedia environments.

The LM4863 features an externally controlled, low-power consumption shutdown mode, a stereo headphone amplifier mode, and thermal shutdown protection. It also utilizes circuitry to reduce "clicks and pops" during device turn-on.

The closed loop response of the unity-gain stable LM4863, can be configured by external gain-setting resistors.

### Key Specifications

- Bridged Mode—THD at 1W continuous average output power into 8Ω 0.5% (max)
- Single-Ended Mode—THD at 75 mW continuous average output power into 32Ω 0.5% (max)
- Shutdown current 0.7 μA (typ)
- Output power at 10% THD+N into 8Ω 1.5W (typ)

### Features

- Stereo Headphone Amplifier Mode
- "Click and Pop" Suppression Circuitry
- Minimal Amount of External Components
- Small Outline and Dual-In-Line Packaging Available
- Unity-Gain Stable
- External Gain Configuration Capability
- Thermal Shutdown Protection Circuitry

### Applications

- Multimedia Monitors
- Portable and Desktop Computers
- Portable Televisions

### Typical Application

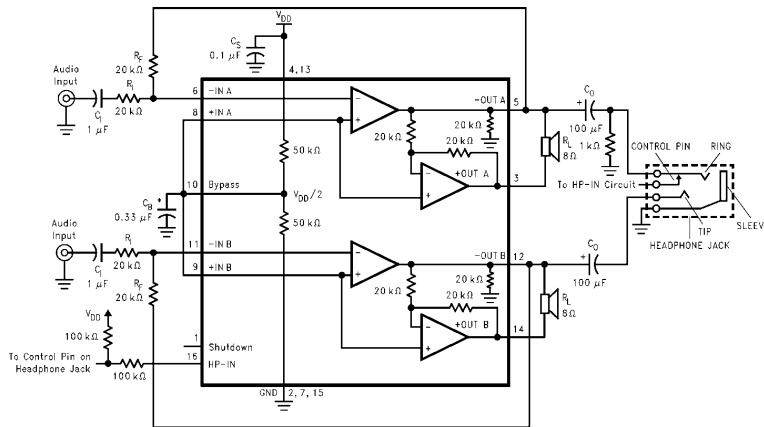
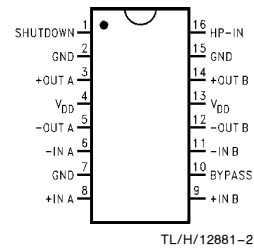


FIGURE 1. Typical Audio Amplifier Application Circuit

\* Refer to the section **Proper Selection of External Components**, for a detailed discussion of  $C_G$  size.

### Connection Diagram



Top View

Order Number LM4863  
See NS Package Number M16B for SO  
See NS Package Number N16A for DIP

LM4863 Dual 1.1W Audio Amplifier plus Stereo Headphone Function

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## Absolute Maximum Ratings

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage	6.0V
Storage Temperature	-65°C to +150°C
Input Voltage	-0.3V to $V_{DD} + 0.3V$
Power Dissipation (Note 3)	Internally limited
ESD Susceptibility (Note 4)	2000V
ESD Susceptibility (Note 5)	200V
Junction Temperature	150°C
Solder Information	
Small Outline Package	
Vapor Phase (60 sec.)	215°C
Infrared (15 sec.)	220°C

See AN-450 "Surface Mounting and their Effects on Product Reliability" for other methods of soldering surface mount devices.

Thermal Resistance

$\theta_{JC}$ (typ)—M16B	20°C/W
$\theta_{JA}$ (typ)—M16B	80°C/W
$\theta_{JC}$ (typ)—N16A	20°C/W
$\theta_{JA}$ (typ)—N16A	63°C/W

## Operating Ratings

Temperature Range

$T_{MIN} \leq T_A \leq T_{MAX}$	-40°C $\leq T_A \leq$ 85°C
Supply Voltage	2.0V $\leq V_{DD} \leq$ 5.5V

## Electrical Characteristics for Entire IC (Notes 1, 2)

The following specifications apply for  $V_{DD} = 5V$  unless otherwise noted. Limits apply for  $T_A = 25^\circ C$ .

Symbol	Parameter	Conditions	LM4863		Units (Limits)
			Typical (Note 6)	Limit (Note 7)	
$V_{DD}$	Supply Voltage			2	V (min)
				5.5	V (max)
$I_{DD}$	Quiescent Power Supply Current	$V_{IN} = 0V, I_O = 0A$ (Note 8), HP-IN = 0V	11.5	20	mA (max)
		$V_{IN} = 0V, I_O = 0A$ (Note 8), HP-IN = 4V	5.8	6	mA (min) mA
$I_{SD}$	Shutdown Current	$V_{PIN1} = V_{DD}$	0.7	2	$\mu A$ (min)
$V_{IH}$	Headphone High Input Voltage			4	V (min)
$V_{IL}$	Headphone Low Input Voltage			0.8	V (max)

## Electrical Characteristics for Bridged-Mode Operation (Notes 1, 2)

The following specifications apply for  $V_{DD} = 5V$  unless otherwise specified. Limits apply for  $T_A = 25^\circ C$ .

Symbol	Parameter	Conditions	LM4863		Units (Limits)
			Typical (Note 6)	Limit (Note 7)	
$V_{OS}$	Output Offset Voltage	$V_{IN} = 0V$	5	50	mV (max)
$P_O$	Output Power	THD = 0.5% (max), $f = 1$ kHz, $R_L = 8\Omega$	1.1	1.0	W (min)
		THD + N = 1%, $f = 1$ kHz, $R_L = 32\Omega$	0.34		W
		THD + N = 10%, $f = 1$ kHz, $R_L = 8\Omega$	1.5		W
THD + N	Total Harmonic Distortion + Noise	$P_O = 1W, 20$ Hz $\leq f \leq 20$ kHz, $A_{VD} = 2$	0.3		%
PSRR	Power Supply Rejection Ratio	$V_{DD} = 5V, V_{RIPPLE} = 200$ mV <sub>RMS</sub> , $R_L = 8\Omega, C_B = 1.0$ $\mu F$	67		dB
$X_{TALK}$	Channel Separation	$f = 1$ kHz, $C_B = 1.0$ $\mu F$	90		dB

## Electrical Characteristics for Single-Ended Operation (Notes 1, 2)

The following specifications apply for  $V_{DD} = 5V$  unless otherwise specified. Limits apply for  $T_A = 25^\circ C$ .

Symbol	Parameter	Conditions	LM4863		Units (Limits)
			Typical (Note 6)	Limit (Note 7)	
$V_{OS}$	Output Offset Voltage	$V_{IN} = 0V$	5	50	mV (max)
$P_O$	Output Power	THD = 0.5%, $f = 1\text{ kHz}$ , $R_L = 32\Omega$ THD + N = 1%, $f = 1\text{ kHz}$ , $R_L = 8\Omega$ THD + N = 10%, $f = 1\text{ kHz}$ , $R_L = 8\Omega$	85 340 440	75	mW (min) mW mW
THD + N	Total Harmonic Distortion + Noise	$A_V = -1$ , $P_O = 75\text{ mW}$ , $20\text{ Hz} \leq f \leq 20\text{ kHz}$ , $R_L = 32\Omega$	0.2		%
PSRR	Power Supply Rejection Ratio	$C_B = 1.0\ \mu F$ , $V_{RIPPLE} = 200\text{ mV}_{RMS}$ , $f = 1\text{ kHz}$	52		dB
XTALK	Channel Separation	$f = 1\text{ kHz}$ , $C_B = 1.0\ \mu F$	60		dB

**Note 1:** All voltages are measured with respect to the ground pins, 2, 7, and 15, unless otherwise specified.

**Note 2:** Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

**Note 3:** The maximum power dissipation must be derated at elevated temperatures and is dictated by  $T_{JMAX}$ ,  $\theta_{JA}$ , and the ambient temperature  $T_A$ . The maximum allowable power dissipation is  $P_{DMAX} = (T_{JMAX} - T_A)/\theta_{JA}$ . For the LM4863,  $T_{JMAX} = 150^\circ C$ , and the typical junction-to-ambient thermal resistance, when board mounted, is  $80^\circ C/W$  assuming the M16B package.

**Note 4:** Human body model, 100 pF discharged through a 1.5 k $\Omega$  resistor.

**Note 5:** Machine model, 220 pF–240 pF discharged through all pins.

**Note 6:** Typicals are measured at  $25^\circ C$  and represent the parametric norm.

**Note 7:** Limits are guaranteed to National's AOQL (Average Outgoing Quality Level).

**Note 8:** The quiescent power supply current depends on the offset voltage when a practical load is connected to the amplifier.

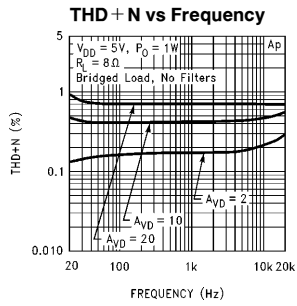
## Truth Table for Logic Inputs

SHUTDOWN	HP-IN	LM4863 MODE
Low	Low	Bridged
Low	High	Single-Ended
High	Low	LM4863 Shutdown
High	High	LM4863 Shutdown

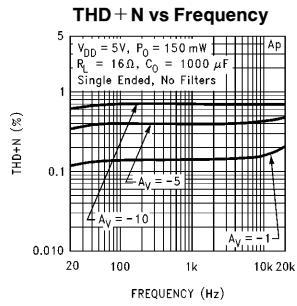
## External Components Description (Figure 1)

Components	Functional Description
1. $R_i$	Inverting input resistance which sets the closed-loop gain in conjunction with $R_f$ . This resistor also forms a high pass filter with $C_i$ at $f_c = 1/(2\pi R_i C_i)$ .
2. $C_i$	Input coupling capacitor which blocks the DC voltage at the amplifier's input terminals. Also creates a highpass filter with $R_i$ at $f_c = 1/(2\pi R_i C_i)$ . Refer to the section, <b>Proper Selection of External Components</b> , for an explanation of how to determine the value of $C_i$ .
3. $R_f$	Feedback resistance which sets the closed-loop gain in conjunction with $R_i$ .
4. $C_S$	Supply bypass capacitor which provides power supply filtering. Refer to the <b>Power Supply Bypassing</b> section for information concerning proper placement and selection of the supply bypass capacitor.
5. $C_B$	Bypass pin capacitor which provides half-supply filtering. Refer to the section, <b>Proper Selection of External Components</b> , for information concerning proper placement and selection of $C_B$ .

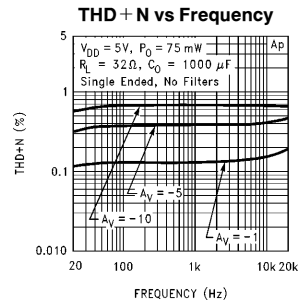
## Typical Performance Characteristics



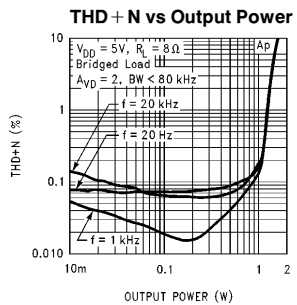
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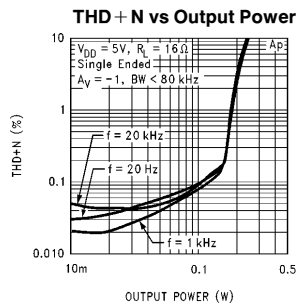
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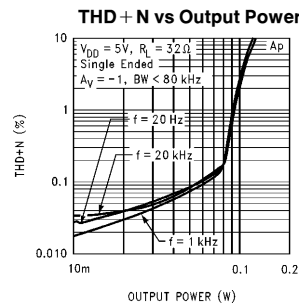
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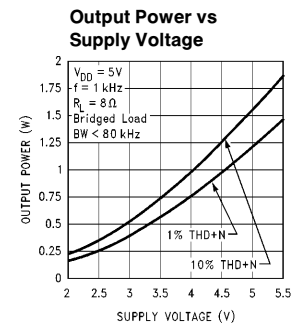
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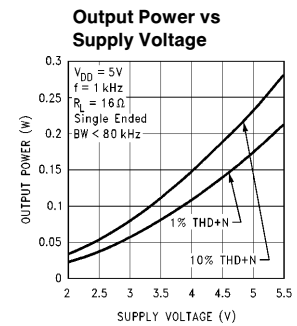
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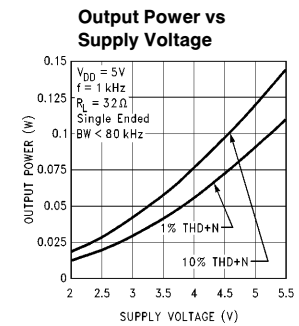
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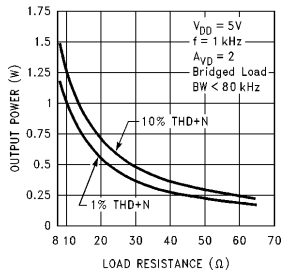
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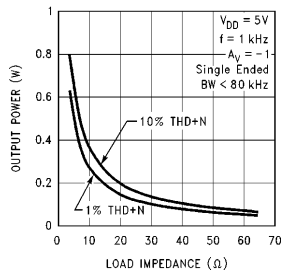
## Typical Performance Characteristics (Continued)

**Output Power vs Load Resistance**



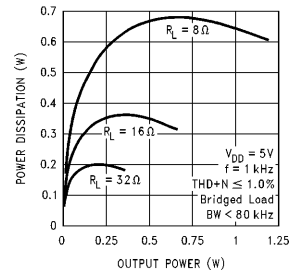
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**Output Power vs Load Impedance**



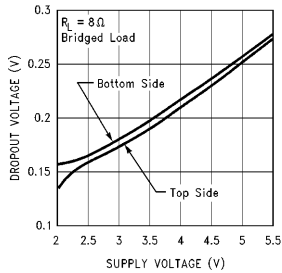
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**Power Dissipation vs Output Power**



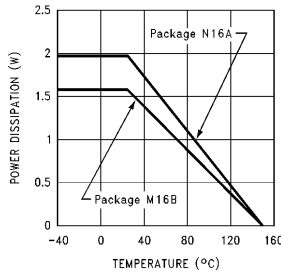
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**Dropout Voltage vs Supply Voltage**



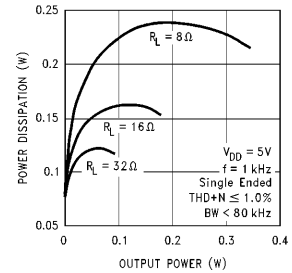
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**Power Derating Curve**



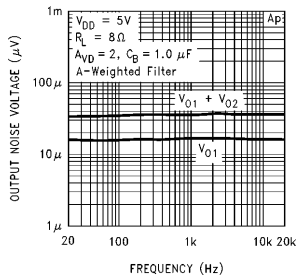
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**Power Dissipation vs Output Power**



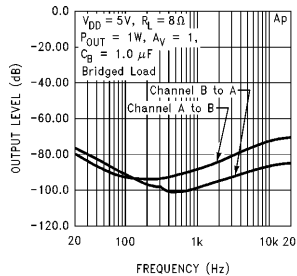
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**Noise Floor**



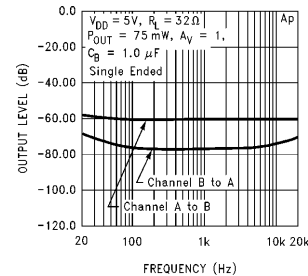
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**Channel Separation**



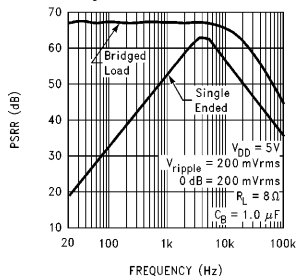
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**Channel Separation**



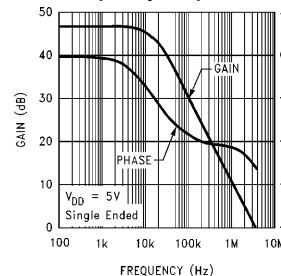
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**Power Supply Rejection Ratio**



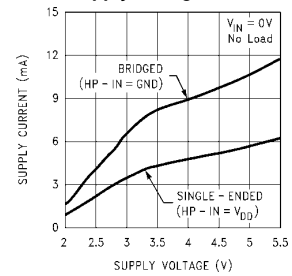
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**Open Loop Frequency Response**



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**Supply Current vs Supply Voltage**



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## Application Information

### BRIDGE CONFIGURATION EXPLANATION

As shown in *Figure 1*, the LM4863 has two pairs of operational amplifiers internally, allowing for a few different amplifier configurations. The first amplifier's gain is externally configurable, while the second amplifier is internally fixed in a unity-gain, inverting configuration. The closed-loop gain of the first amplifier is set by selecting the ratio of  $R_f$  to  $R_i$  while the second amplifier's gain is fixed by the two internal 20 k $\Omega$  resistors. *Figure 1* shows that the output of amplifier one serves as the input to amplifier two which results in both amplifiers producing signals identical in magnitude, but out of phase 180°. Consequently, the differential gain for each channel of the IC is

$$A_{VD} = 2 * (R_f/R_i)$$

By driving the load differentially through outputs +OutA and -OutA or +OutB and -OutB, an amplifier configuration commonly referred to as "bridged mode" is established. Bridged mode operation is different from the classical single-ended amplifier configuration where one side of its load is connected to ground.

A bridge amplifier design has a few distinct advantages over the single-ended configuration, as it provides differential drive to the load, thus doubling the output swing for a specified supply voltage. Four times the output power is possible as compared to a single-ended amplifier under the same conditions. This increase in attainable output power assumes that the amplifier is not current limited or clipped. In order to choose an amplifier's closed-loop gain without causing excessive clipping, please refer to the **Audio Power Amplifier Design** section.

A bridge configuration, such as the one used in LM4863, also creates a second advantage over single-ended amplifiers. Since the differential outputs, +OutA, -OutA, +OutB, and -OutB, are biased at half-supply, no net DC voltage exists across the load. This eliminates the need for an output coupling capacitor which is required in a single supply, single-ended amplifier configuration. If an output coupling capacitor is not used in a single-ended configuration, the half-supply bias across the load would result in both increased internal IC power dissipation as well as permanent loudspeaker damage.

### POWER DISSIPATION

Power dissipation is a major concern when designing a successful amplifier, whether the amplifier is bridged or single-ended. Equation 1 states the maximum power dissipation point for a single-ended amplifier operating at a given supply voltage and driving a specified load.

$$P_{DMAX} = (V_{DD})^2 / (2\pi^2 R_L) \quad \text{Single-Ended (1)}$$

However, a direct consequence of the increased power delivered to the load by a bridge amplifier is an increase in internal power dissipation. Equation 2 states the maximum power dissipation point for a bridge amplifier operating at the same given conditions.

$$P_{DMAX} = 4 * (V_{DD})^2 / (2\pi^2 R_L) \quad \text{Bridge Mode (2)}$$

Since the LM4863 is a dual channel power amplifier, the maximum internal power dissipation is 2 times that of Equation 1 or Equation 2 depending on the mode of operation. Even with this substantial increase in power dissipation, the LM4863 does not require heatsinking. The power dissipation from Equation 2, assuming a 5V power supply and an 8 $\Omega$  load, must not be greater than the power dissipation that results from Equation 3:

$$P_{DMAX} = (T_{JMAX} - T_A) / \theta_{JA} \quad (3)$$

For package M16A,  $\theta_{JA} = 80^\circ\text{C/W}$ , and for package N16A,  $\theta_{JA} = 63^\circ\text{C/W}$ .  $T_{JMAX} = 150^\circ\text{C}$  for the LM4863. Depending on the ambient temperature,  $T_A$ , of the system surroundings, Equation 3 can be used to find the maximum internal power dissipation supported by the IC packaging. If the result of Equation 2 is greater than that of Equation 3, then either the supply voltage must be decreased, the load impedance increased, or the ambient temperature reduced. For the typical application of a 5V power supply, with an 8 $\Omega$  bridged load, the maximum ambient temperature possible without violating the maximum junction temperature is approximately 48°C provided that device operation is around the maximum power dissipation point and assuming surface mount packaging. Internal power dissipation is a function of output power. If typical operation is not around the maximum power dissipation point, the ambient temperature can be increased. Refer to the **Typical Performance Characteristics** curves for power dissipation information for different output powers.

### POWER SUPPLY BYPASSING

As with any power amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both the bypass and power supply pins should be as close to the device as possible. The effect of a larger half supply bypass capacitor is improved PSRR due to increased half-supply stability. Typical applications employ a 5V regulator with 10  $\mu\text{F}$  and a 0.1  $\mu\text{F}$  bypass capacitors which aid in supply filtering. This does not eliminate the need for bypassing the supply nodes of the LM4863. The selection of bypass capacitors, especially  $C_B$ , is thus dependent upon desired PSRR requirements, click and pop performance as explained in the section, **Proper Selection of External Components**, system cost, and size constraints.

### SHUTDOWN FUNCTION

In order to reduce power consumption while not in use, the LM4863 contains a shutdown pin to externally turn off the amplifier's bias circuitry. This shutdown feature turns the amplifier off when a logic high is placed on the shutdown pin. The trigger point between a logic low and logic high level is typically half supply. It is best to switch between ground and the supply  $V_{DD}$  to provide maximum device performance. By switching the shutdown pin to  $V_{DD}$ , the LM4863 supply current draw will be minimized in idle mode. While the device will be disabled with shutdown pin voltages less than  $V_{DD}$ , the idle current may be greater than the typical value of 0.7  $\mu\text{A}$ . In either case, the shutdown pin should be tied to a definite voltage to avoid unwanted state changes.



## Application Information (Continued)

Besides gain, one of the major considerations is the closed-loop bandwidth of the amplifier. To a large extent, the bandwidth is dictated by the choice of external components shown in *Figure 1*. The input coupling capacitor,  $C_i$ , forms a first order high pass filter which limits low frequency response. This value should be chosen based on needed frequency response for a few distinct reasons.

### CLICK AND POP CIRCUITRY

The LM4863 contains circuitry to minimize turn-on transients or “clicks and pops”. In this case, turn-on refers to either power supply turn-on or the device coming out of shutdown mode. When the device is turning on, the amplifiers are internally configured as unity gain buffers. An internal current source ramps up the voltage of the bypass pin. Both the inputs and outputs ideally track the voltage at the bypass pin. The device will remain in buffer mode until the bypass pin has reached its half supply voltage,  $1/2 V_{DD}$ . As soon as the bypass node is stable, the device will become fully operational, where the gain is set by the external resistors.

Although the bypass pin current source cannot be modified, the size of  $C_B$  can be changed to alter the device turn-on time and the amount of “clicks and pops”. By increasing amount of turn-on pop can be reduced. However, the tradeoff for using a larger bypass capacitor is an increase in turn-on time for this device. There is a linear relationship between the size of  $C_B$  and the turn-on time. Here are some typical turn-on times for a given  $C_B$ :

$C_B$	$T_{ON}$
0.01 $\mu F$	20 ms
0.1 $\mu F$	200 ms
0.22 $\mu F$	420 ms
0.47 $\mu F$	840 ms
1.0 $\mu F$	2 Sec

In order eliminate “clicks and pops”, all capacitors must be discharged before turn-on. Rapid on/off switching of the device or the shutdown function may cause the “click and pop” circuitry to not operate fully, resulting in increased “click and pop” noise. In a single-ended configuration, the output coupling capacitor,  $C_O$ , is of particular concern. This capacitor discharges through the internal 20 k $\Omega$  resistors. Depending on the size of  $C_O$ , the time constant can be relatively large. To reduce transients in single-ended mode, an external 1 k $\Omega$ –5 k $\Omega$  resistor can be placed in parallel with the internal 20 k $\Omega$  resistor. The tradeoff for using this resistor is an increase in quiescent current.

The value of  $C_i$  will also reflect turn-on pops. Clearly, a certain size for  $C_i$  is needed to couple in low frequencies without excessive attenuation. But in many cases, the speakers used in portable systems, whether integral or external, have little ability to reproduce signals below 100 Hz to 150 Hz. In this case, using a large input and output capacitor may not increase system performance. In most cases, choosing a small value of  $C_i$  in the range of 0.1  $\mu F$  to 0.33  $\mu F$ , along with  $C_B$  equal to 1.0  $\mu F$  should produce a virtually clickless and popless turn-on. In cases where  $C_i$  is larger than 0.33  $\mu F$ , it may be advantageous to increase the value of  $C_B$ . Again, it should be understood that increasing the value of  $C_B$  will reduce the “clicks and pops” at the expense of a longer device turn-on time.

## AUDIO POWER AMPLIFIER DESIGN

### Design a 1W/8 $\Omega$ Bridged Audio Amplifier

Given:

Power Output	1 Wrms
Load Impedance	8 $\Omega$
Input Level	1 Vrms
Input Impedance	20 k $\Omega$
Bandwidth	100 Hz–20 kHz $\pm$ 0.25 dB

A designer must first determine the minimum supply rail to obtain the specified output power. By extrapolating from the Output Power vs Supply Voltage graphs in the **Typical Performance Characteristics** section, the supply rail can be easily found. A second way to determine the minimum supply rail is to calculate the required  $V_{Opeak}$  using Equation 3 and add the dropout voltage. Using this method, the minimum supply voltage would be  $(V_{Opeak} + (2 * V_{Ood}))$ , where  $V_{Ood}$  is extrapolated from the Dropout Voltage vs Supply Voltage curve in the **Typical Performance Characteristics** section.

$$V_{Opeak} = \sqrt{(2R_L P_O)} \quad (3)$$

Using the Output Power vs Supply Voltage graph for an 8 $\Omega$  load, the minimum supply rail is 3.9V. But since 5V is a standard supply voltage in most applications, it is chosen for the supply rail. Extra supply voltage creates headroom that allows the LM4863 to reproduce peaks in excess of 1W without producing audible distortion. At this time, the designer must make sure that the power supply choice along with the output impedance does not violate the conditions explained in the **Power Dissipation** section.

Once the power dissipation equations have been addressed, the required differential gain can be determined from Equation 4.

$$A_{VD} \geq \sqrt{(P_O R_L)} / (V_{IN}) = V_{Orms} / V_{Inrms} \quad (4)$$

$$R_f / R_i = A_{VD} / 2 \quad (5)$$

From equation 4, the minimum  $A_{VD}$  is 2.83; use  $A_{VD} = 3$ . Since the desired input impedance was 20 k $\Omega$ , and with a  $A_{VD}$  of 3, a ratio of 1.5:1 of  $R_f$  to  $R_i$  results in an allocation of  $R_i = 20$  k $\Omega$  and  $R_f = 30$  k $\Omega$ . The final design step is to address the bandwidth requirements which must be stated as a pair of  $-3$  dB frequency points. Five times away from a pole gives 0.17 dB down from passband response, which is better than the required  $\pm 0.25$  dB specified.

$$f_L = 100 \text{ Hz} / 5 = 20 \text{ Hz}$$

$$f_H = 20 \text{ kHz} \times 5 = 100 \text{ kHz}$$

As stated in the **External Components** section,  $R_i$  in conjunction with  $C_i$  create a highpass filter.

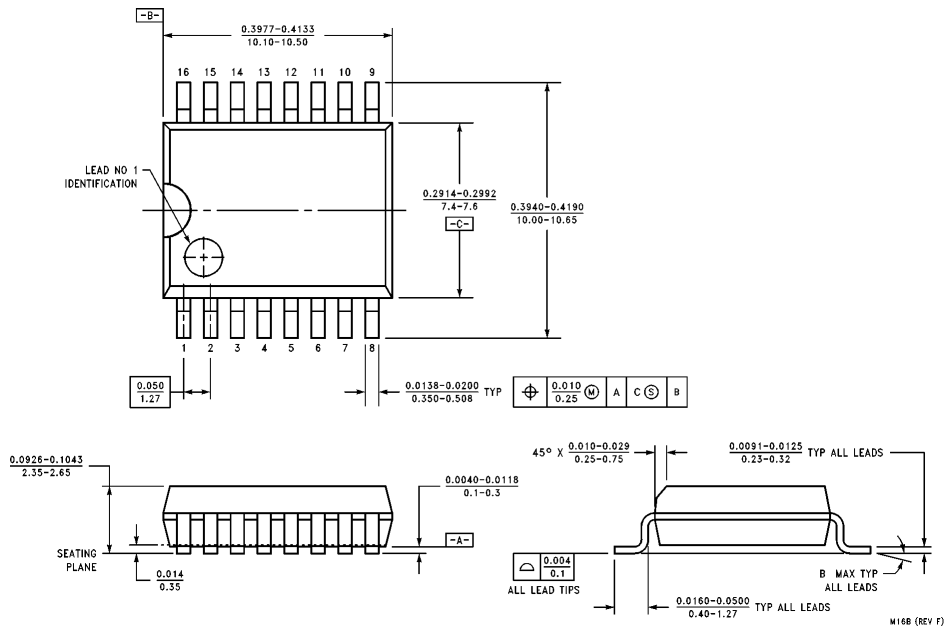
$$C_i \geq \frac{1}{2\pi R_i f_c}$$

$$C_i \geq 1 / (2\pi * 20 \text{ k}\Omega * 20 \text{ Hz}) = 0.397 \mu F; \text{ use } 0.33 \mu F$$

The high frequency pole is determined by the product of the desired high frequency pole,  $f_H$ , and the differential gain,  $A_{VD}$ . With a  $A_{VD} = 3$  and  $f_H = 100$  kHz, the resulting GBWP = 150 kHz which is much smaller than the LM4863 GBWP of 3.5 MHz. This figure displays that if a designer has a need to design an amplifier with a higher differential gain, the LM4863 can still be used without running into bandwidth problems.



**Physical Dimensions** inches (millimeters) unless otherwise noted



**16-Lead (0.300" Wide) Molded Small Outline Package, JEDEC  
Order Number LM4863  
NS Package Number M16B**

M16B (REV F)

